

Significance of the colour code

	Pinion number or rotor (output component)
	Sealing rotor (sealing component)
	Alternating or simultaneous pinion or rotor and sealing component
	
	Stationary chamber wall
	Crank
	Sealing element

Illustrations of engagement methods

Internal-axis SIM

Similar arrangement to the axes of an external/teeth gear meshing with internal tooth ring gear

Principle of Engagement	I. Reciprocating engagement (R)	II. Axial engagement (A)	III. Cam engagement (Ce) or (C)	IV. Slip engagement (S)	V. Output engagement (Oe) or (Oa)
Example of module	impossible as SIM machines				
Diagrams, sketch, arrows indicate direction of rotation					
Distinguishing mark		At point of contact the rotating parts have in same direction. Engaging parts pursue parallel circular paths. This involves at equal r.p.m.	At point of contact motion is in same direction. Engaging component with smaller diameter and higher speed has fewer teeth. Larger diameter part rotating at lower speed has more teeth.	At contact point rotation is same direction. Larger diameter and with higher speed has fewer teeth. Smaller diameter part with lower speed has more teeth.	Direction of rotation at contact point is opposite direction. Speed ratio may be anything provided it is a whole number.
Gear combinations between axes					

External-axis SIM

Similar to the axes of a pair of meshing spur gears

Principle of Engagement	I. Reciprocating engagement (R)	II. Axial engagement (A)	III. Can engagement (C) or (Ca)	IV. Slip engagement (S)	V. Coupled engagement (Co) or (Coa)
Example of motion	Impossible as SIM machines	Impossible with external-axis SIM machines		Can engagement cannot form chainless set external-axis machines.	
Diagrammatic sketch, arrows indicate direction of rotation					
Distinguishing mark			At contact point rotation in same direction. Component with equal or unequal diameter and higher speed has fewer teeth. Component with equal or unequal diameter and lower speed has more teeth. Component with equal or unequal diameter and same speed has equal number of teeth.		Direction of rotation at contact point is opposite diagram. Speed ratio may be anything provided it is a whole number.
Gear combinations between axes					

Internal-axis PLM with inner piston-rotor similar to the arrangement of axes of piston and internal-teeth ring gear, the piston/rotor revolving about its own centre of gravity

Principle of Engagement	I. Reciprocating engagement (R)	II. Axial engagement (A)	III. Can engagement (C) or (Ca)	IV. Slip engagement (S)	V. Coupled engagement (Co) or (Coa)
Example of motion					
Diagrammatic sketch, arrows indicate direction of rotation					
Distinguishing mark	Linear motion between the engaging components. Piston-rotor revolves in opposite direction to crank of both crank speed relative to housing. Leading component also rotates in same direction at both crank speed relative to housing.	Circular parallel motion of the engaging components. Piston-rotor revolves in opposite direction to crank but at the same speed as the crank relative to the casing.	Rolling motion at engagement point. Piston-rotor revolves in opposite direction to crank but at higher speed than the crank relative to casing. Engaging component with inner diameter and higher speed has smaller number of teeth. Engaging component with larger diameter has more teeth.	Rolling motion at engagement point. Piston-rotor revolves in opposite direction to crank but at lower speed relative to casing. Engaging component with larger diameter has fewer teeth. Engaging component with smaller diameter and lower speed has more teeth.	Counter movement at point of contact. Piston-rotor revolves at equal speed round crank pin at any crank ratio to crank relative to casing provided it is a whole number.
Gear combinations between axes					

Internal-axis PLM with outer piston-rotor similar to the arrangement of axes of pinion and internal tooth ring gear, piston-rotor rotating about its own centre of gravity

Principle of Engagement	I. Reciprocating engagement (R)	II. Arcuate engagement (A)	III. Cam engagement (C ₁) or (C ₂)	IV. Slip engagement (S)	V. Counter engagement (C ₁) or (C ₂)
Example of models					
Diagrammatic models, arrows indicate direction of rotation					
Distinguishing mark	Linear motion of engaging components. Piston-rotor revolves in opposite direction to crank at full crank speed relative to housing. Sliding component also rotates in same direction at full crank speed relative to housing.	Circular parallel motion of the engaging components. Piston-rotor revolves in opposite direction to crank but at the same speed as the crank relative to the housing.	Rolling motion at engagement point. Piston-rotor revolves in opposite direction to crank at least equal from the crank relative to housing. Engaging component with smaller diameter has fewer teeth. Larger diameter part with lower speed has more teeth.	Rolling motion at engagement point. Piston-rotor revolves in opposite direction to crank at higher speed relative to housing. Engaging component with larger diameter and higher speed has fewer teeth. Larger diameter part has more teeth.	Counter movement at point of contact. Piston-rotor revolves at equal speed round crank pin at any crank ratio to crank, relative to housing provided it is a whole number.
Gear connections between axes					

External-axis PLM have axes similarly arranged to meshing spur gears and the rotating piston-rotor revolves round its c.g. which itself follows a circular path

Principle of Engagement	I. Reciprocating engagement (R)	II. Arcuate engagement (A)	III. Cam engagement (C ₁) or (C ₂)	IV. Slip engagement (S)	V. Counter engagement (C ₁) or (C ₂)
Example of models					
Diagrammatic models, arrows indicate direction of rotation					
Distinguishing mark	Linear motion of engaging components. Piston-rotor revolves in opposite direction to crank and at the same speed relative to the housing. Crankshaft rotate in opposite direction.	Circular parallel motion of the engaging components. Piston-rotor revolves in opposite direction to crank and at the same speed relative to housing. Crankshaft rotate in the same direction.	Rolling motion at engaging point. Piston-rotor revolves in the same direction relative to housing. Engaging component with equal or unequal diameters and higher speeds have fewer teeth. Engaging component with equal or unequal diameters and lower speeds have more teeth. Engaging component with equal or unequal diameters have equal number of teeth.	Slip engagement cannot form definition in external-axis machines.	Counter rolling movement at contact point. Piston-rotor revolves in opposite direction to crank pin at any crank ratio to crank, provided it is a whole number.
Gear connections between axes					

	INTERNATIONAL						USA						TOTAL
	1950	1951	1952	1953	1954	1955	1950	1951	1952	1953	1954	1955	
1. Total													
2. American													
3. European													
4. Other													
5. Total													
6. American													
7. European													
8. Other													
9. American													
10. European													
11. Other													
12. American													
13. European													
14. Other													
15. American													
16. European													
17. Other													
18. American													
19. European													
20. Other													