ENUMERATION OF THE ELEMENTARY CIRCUITS OF A DIRECTED GRAPH

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Abstract:

An algorithm to enumerate all the elementary circuits of a directed graph is presented. The algorithm uses backtracking with lookahead to avoid unnecessary work, and it has a time bound of \( O((V + E)(C+1)) \) when applied to a graph with \( V \) vertices, \( E \) edges, and \( C \) elementary circuits.

Keywords: Algorithm, circuit, cycle, graph
Many applications require the enumeration of a certain set of objects associated with a given graph. In some cases the number of objects may grow exponentially with the number of vertices in the graph; thus there are no algorithms with time bounds polynomial in the size of the graph for solving such problems. Examples include enumerating the elementary circuits, the spanning trees, or the cliques of a given graph. However, it may be possible to find algorithms with time bounds polynomial (and hopefully linear) in the number of objects generated. Presented here is an algorithm for enumerating elementary circuits in a graph which is "good" in this sense.

A (directed) graph \( G=(\mathcal{V}, \mathcal{E}) \) consists of a set of vertices \( \mathcal{V} \) and a set of ordered pairs of vertices \( \mathcal{E} \), called the edges of \( G \). If \((v,w)\) is an edge of \( G \), vertices \( v \) and \( w \) are said to be adjacent. A path in a graph is a sequence of edges \((v_1, v_2)\) \((v_2, v_3)\) \(\ldots\) \((v_{n-1}, v_n)\) such that the terminal vertex of an edge in the sequence is the initial vertex of the next edge. A path may be denoted by the sequence of vertices on it. An elementary path contains no vertex twice. An elementary circuit is an elementary path with the exception that its first and last vertices are identical. For simplicity we shall assume that a graph contains no self-loops (edges of the form \((v,v)\)) and no multiple edges.

We wish to enumerate all the elementary circuits of a given graph. Tiernan [2] presents an algorithm for accom-
plishing this. His algorithm uses an essentially unconstrained backtracking procedure which explores elementary paths of the graph and checks to see if they are cycles. If the vertices of the graph are numbered from 1 to \( V \), the algorithm will generate all elementary paths \( p = (v_1, v_2, \ldots, v_k) \) with \( v_1 < v_i \) for all \( 2 \leq i \leq k \), by starting from some vertex \( v_1 \), choosing an edge to traverse to some vertex \( v_2 > v_1 \), and continuing in this way. Whenever no new vertex can be reached, the procedure backs up one vertex and chooses a different edge to traverse. If \( v_1 \) is adjacent to \( v_k \), the algorithm lists an elementary cycle \( (v_1, v_2, \ldots, v_k, v_1) \).

The algorithm enumerates each elementary cycle exactly once, since each such cycle contains a unique smallest vertex \( v_1 \) and thus corresponds to a unique elementary path with starting vertex \( v_1 \). However, the algorithm is not a "good" one, because it explores many more elementary paths than are necessary. Consider the graph \( G \) in Figure 1. It contains \( 3n+1 \) vertices, \( 5n \) edges, and \( 2n \) elementary circuits. However, \( G \) contains \( 2^n \) elementary paths from vertex 1 to vertex \( 3n+1 \), all of which will be generated by Tiernan's algorithm. Thus the worst case time bound of the algorithm is exponential in the number of elementary circuits, as well as exponential in the size of the graph.

Weinblatt [3] gives an algorithm for finding elementary circuits which is related to Tiernan's, but which requires substantially more bookkeeping. Weinblatt uses a depth-first search to explore the graph. A general description of the depth-first search technique appears in [1]. Given a graph \( G \), we start from some vertex and choose an edge to follow. This edge leads to a
new vertex. We continue in this way; at each step we select an unexplored edge leading from a vertex already reached and we traverse this edge. The edge leads to some vertex, either new or already reached. Whenever we run out of edges leading from old vertices we choose some unreached vertex, if any, and begin a new exploration from this point. Eventually we will traverse all the edges of G, each exactly once. (A backtrack-ing procedure such as Tiernan's may traverse each edge of a graph many times.) Such a process is called a search of G. Suppose we use the following choice rule to select the next edge to traverse: always choose an edge emanating from the vertex most recently reached which still has unexplored edges. A search which uses this rule is a depth-first search.
A depth-first search is easy to program, because the set of old vertices with possibly unexplored edges may be stored on a stack. This sequence of vertices is an elementary path from the initial vertex to the vertex currently being examined. (Weinblatt calls it the TT, or "trial thread".) Whenever we traverse an edge leading to a vertex already on the stack, we have found a new elementary circuit, corresponding to a sequence of vertices on top of the stack. Whenever we traverse an edge leading to an old vertex which is not currently on the stack, some portion of the stack plus a sequence of subpaths from circuits already found may form a new elementary circuit. Weinblatt uses a recursive backtracking procedure to test combinations of subpaths from old circuits to see if they give new circuits in this way.

Although Weinblatt's algorithm is often much more efficient than Tiernan's, the recursive backtracking procedure requires exponential time in the worst case. For example, consider the graph in Figure 2. It contains 3n+2 vertices, 5n+3 edges, and 2n+2 elementary circuits. Suppose we start Weinblatt's algorithm by exploring the edge (0,1). Then the algorithm will generate all circuits of the form (3i-2,3i+1,3i,3i-2) and (3i-2, 3i+1, 3i-1, 3i-2) rapidly. Eventually the algorithm will traverse edge (0,3n+1). Then Weinblatt's recursive procedure will attempt to find an elementary path back to vertex 0 by combining parts of old cycles. The recursive backtracking will require an exponential amount of time but will produce only one new
cycle; namely $(0, 3n+1, 0)$. Thus Weinblatt's algorithm is not "good" in the sense we desire.

However, it is possible to construct a "good" algorithm for the circuit enumeration problem. Such an algorithm uses a backtracking procedure restricted so that only fruitful paths are explored. The circuit enumeration algorithm is presented below in Algol-like notation. The algorithm assumes that the vertices of the graph are numbered from 1 to $V$, and that the graph is represented by a set of adjacency lists, one for each vertex. The adjacency list $A(v)$ of vertex $v$ contains all vertices $w$ such that $(v, w)$ is an edge of the graph. The point stack used in the algorithm denotes the elementary path $p$ currently being considered; the elementary path has start vertex $s$. Every vertex $v$ on such a path must satisfy $v > s$. A vertex $v$ is marked if it is on the elementary path $p$ or if every path leading from $v$ to $s$ intersects $p$ at a point other than $s$.

For each vertex $s$, the algorithm generates elementary paths which start at $s$ and contain no vertex smaller than $s$. Once a vertex $v$ has been used in a path, it can only be used in a new path when it has been deleted from the point stack and when it becomes unmarked. A vertex $v$ becomes unmarked when a path from $v$ to $s$ which does not intersect the current elementary path other than at $s$ is found. Whenever the last vertex on an elementary path is adjacent to the start vertex $s$, the elementary path corresponds to an elementary circuit which is enumerated.
procedure circuit Enumeration;
begin
  procedure BACKTRACK(integer value v, logical result f);
  begin
    logical g;
    f := false;
    place v on point stack;
    mark(v) := true;
    place v on marked stack;
    for w ∈ A(v) do
      if w < s then delete w from A(v);
    else if w = s then
      begin
        output circuit from s to v to s given by point stack;
        f := true;
      end;
    else if ¬ mark(w) then
      begin
        BACKTRACK(w, g);
        f := f ∨ g;
      end;
  comment f = true if an elementary circuit continuing the
  partial path on the stack has been found;
  if f = true then
    begin
      while top of marked stack ≠ v do
        begin
          u := top of marked stack;
          delete u from marked stack;
          mark(u) := false;
        end;
delete v from marked stack;

mark(v) := false;

end;

delete v from point stack;

end;

integer n;

for i:=1 until v do mark(i) := false;
for s:=1 until v do

begin

BACKTRACK(s, flag);

while marked stack not empty do

begin

u := top of marked stack;

mark(u) := false;

delete u from marked stack;

end;

end;

end;
**Lemma 1:** Let \( c = (v_1, v_2, \ldots, v_n, v_1) \) be an elementary circuit in a graph \( G \). Consider applying \( \text{BACKTRACK}(v_1) \) to \( G \). For all \( 1 \leq k \leq n, v_k \) will be unmarked unless, for some \( j \geq k, v_j \) is on the stack.

**Proof:** Vertex \( v_n \) is unmarked unless it is on the stack, since \((v_n, v_1)\) is an edge of the graph and an elementary circuit containing \( v_n \) will be found each time \( v_n \) is placed on the stack, causing \( v_n \) to be unmarked whenever it is removed from the stack.

Let the Lemma be true for \( v_i \) with \( i > k \). Suppose \( v_k \) is placed on the stack. If \( v_k \) is placed on top of some \( v_j, j > k \), then \( v_k \) will become unmarked before \( v_j \) becomes unmarked (since \( v_k \) appears on top of \( v_j \) in the marked stack). While \( v_j \) is marked, there is some \( v_\ell \) with \( \ell \geq j \) on the stack by the induction hypothesis, and since \( \ell \geq j > k \) the Lemma holds for \( v_k \).

On the other hand if \( v_k \) is not placed on top of any \( v_j, j > k \), then by the induction hypothesis all the \( v_j, j > k \), are unmarked. Thus when the edge \((v_k, v_{k+1})\) is examined, \( v_{k+1} \) will be unmarked and will be added to the stack. Subsequently \( v_{k+2}, v_{k+3}, \ldots, v_n \) will be added to the stack and an elementary circuit containing \( v_k \) will be found. Thus \( v_k \) will be unmarked when it is removed from the point stack and the Lemma holds for \( v_k \). By induction the Lemma holds in general.

**Lemma 2:** The circuit enumeration algorithm lists each elementary circuit of a given graph exactly once.

**Proof:** The starting vertex of any elementary path \( p \) generated by the algorithm is the lowest numbered vertex in the path \( p \).
Since the algorithm generates an elementary path at most once, and since an elementary circuit has only one lowest numbered vertex, each elementary circuit is generated at most once.

Let \( c = (v_1, v_2, \ldots, v_n, v_1) \) be an elementary circuit. Consider the application of \( \text{BACKTRACK}(v_1) \) to a graph. If \( (v_1, \ldots, v_k) \) is on the point stack for any \( 1 \leq k < n \), then by Lemma 1 \( v_{k+1} \) must be unmarked and \( v_{k+1} \) will be added to the point stack on top of \( v_k \) when edge \( (v_k, v_{k+1}) \) is examined. By induction \( (v_1, v_2, \ldots, v_n) \) will eventually be on the point stack, and the algorithm will enumerate the circuit \( c \). Thus each elementary circuit is generated at least once.

Lemma 3: If \( G \) is a graph with \( V \) vertices and \( E \) edges, applying the circuit enumeration algorithm to \( G \) requires \( O(V+E+S) \) space, where \( S \) is the sum of the lengths of all the elementary circuits, and \( O((V+E)(C+1)) \) time, where \( C \) is the number of elementary circuits.

Proof: The space bound is obvious; storage of the graph's adjacency lists requires \( O(V+E) \) space, storage for the algorithm's data structures requires \( O(V) \) space, and storage for the output requires \( O(S) \) space. If we do not want to store all the elementary circuits after they are generated the algorithm requires only \( O(V+E) \) space.

The time bound follows from the observation that after a vertex is marked, it cannot become unmarked until a new circuit is generated. Thus only \( O(V+E) \) time elapses between the generation of two circuits, and the total circuit generation time is \( O((V+E)(C+1)) \). This bound is tight for the algorithm presented here, as one may see by constructing suitable example graphs.
A "good" algorithm for the enumeration of all the elementary circuits of a directed graph has been presented. The algorithm is not only good in the sense that its theoretical time and space bounds are polynomial (in fact, bilinear) in the size of its input and output, but the algorithm is simple to understand, easy to program, and superior to other algorithms in the literature. The algorithm uses backtracking with lookahead, an idea which is easily adaptable to other enumeration problems. It is an open question whether a circuit enumeration algorithm exists whose time bound is linear in the size of its input and output.
References:


Figure 1: An example showing the inefficiency of Tiernan's algorithm.

Figure 2: An example showing the inefficiency of Weinblatt's algorithm.