

INDEX

- Acceleration, 117
 Coriolis, 120, 379, 402, 403
 difference, 120, 125
 image, 20, 128
 normal, 119
 relative, 120
 tangential, 119
- Alt, H., 47
- Ampère, A. M., 14, 22
- Analysis, kinematic, 88, 130
- Archimedes, 3, 70
- Area contact, 34
- Aronhold, 19, 24, 106
- Asymptotes, 154, 156
 four-bar coupler curve, 159
- Autofocus mechanism, 184
-
- Bennett mechanism, 52, 85, 350
- Bernoulli, Johann, 15
- Bernoulli, lemniscate of, 80, 411
- Bétancourt, 12
- Block, S. S., 170
- Bobillier construction, 413
- Bock, A., 48
- Body, resistant, 30
 rigid, 8, 30
- Borgnis, 12, 14
- Bottema, O., 198*n*.
- Bresse, 204
- Bresse circle, 416
- Bricard mechanism, 85
- Burmester, L., 19, 20, 22
-
- Cardan circles, 402, 412
- Cardan universal joint, 50
- Carnot, L. N. M., 11, 23
- Cayley, A., 170, 172, 174
- Centrode, 113
- Chain, constrained, 133, 134
 kinematic, 53, 348
 movable, 134
- Chasles, M., 15, 23
- Chebyshev, P., 22, 23, 176
- Chebyshev, straight-line motion, 146
 (*See also* Roberts-Chebyshev theorem)
- Chebyshev polynomials, 22, 142, 144
- Chebyshev spacing, 142, 147
- Cinématique, 14
- Circle, Bresse, 416
 inflection, 194, 199
- Classification, 16, 18, 29
- Cofactor, 386
- Collineation axis, 413
- Compatibility equation, 309, 331, 337
- Complex numbers, 321, 370
 conjugates, 377
- Components, mechanical, 2
- Connections, 31
 cylindric, 34
 planar, 34
 prismatic, 34, 60
 revolute, 34
 screw, 34
 spheric, 34
- Connectors, 31, 32
 higher-pair, 32

- Connectors, lower-pair, 32
 wrapping, 32, 37
- Constrained chain, 133, 134
- Coriolis, De, 12, 14
- Coriolis acceleration component, 120, 379, 402, 403
- Coupler, 39, 45
 curve, 40, 46, 74
 point, 40
- Cramer's rule, 383, 388
- Crank, 2, 39, 40, 45, 77
- Crosshead, 34
- Crunode, 152, 162, 164
- Cubic of stationary curvature, 195, 207
- Curvature, center of, 194
 centrode, 416
 envelope, 203, 415
 path, 203
 radius of, 194
 stationary, 205
- Curves, center-point, 263
 circle-point, 263
 circling-point, 195
 coupler-point, 15, 16, 40
 asymptotes of, 159
 atlas of, 186
 equation of, 151
 symmetry of, 166
 triple generation of, 161
 second order, 154
 asymptotes of, 156
 three-bar, 150
- Cusp, 152, 162
- D'Alembert, 8
- Davis steering gear, 66
- De Coriolis, 12, 14
- De Jonge, A. E. R., 21, 22
- De la Hire, 204
- De Moivre theorem, 376
- Description, symbolic, 65
- Determinants, 380
 characteristic, 391
 principal, 391
- Deviation angle, 48
- Directions, normal, radial, tangential, transverse, 93
- Displacement, 92
- Eccentric, 59
- Element, 17, 35, 347
 full, 35
 hollow, 35
 interrupted, 37
- Elliptic trammel, 56, 402
- Engine, 28
 Newcomen atmospheric, 14
 Watt rotative, 15, 41
- Equations, compatibility, 309, 331, 337
 homogeneous, 394
 linear algebraic, 380, 389
 symbolic, 343, 348
- Error, derivative of, 142, 281
 graphical, 299
 mechanical, 299, 315
 structural, 141, 230
 velocity, 144
- Euler, L., 7, 8, 23, 204
- Euler-Savary equation, 94, 200, 201
- Euler's theorem, 374
- Farish, W., 70
- Ferguson, E. S., 22
- Follower, 39, 45
- Four-bar linkage, 19, 38
 cognates of, 168
 four-bar, 169, 337
 six-bar, 179
 displacement equation, 296, 297
- Frame, 38, 45, 92
 reference, 31
- Freedom, degrees of, 133
- Freudenstein, F., 22
- Freudenstein equation, 297*n*.
- Function generator, 40, 138, 225
- Garnier, R., 204
- Gauss-Argand plane, 375
- Goldberg mechanism, 85

- Goodman, 20
 Grashof criterion, 77, 134
 Grübler, M, 21, 24, 134
- Hachette, 12
 Hall, A. S., Jr., 195, 210
 Hammer, trip, 6
 Hart, H., 170, 186
 Hero of Alexandria, 2, 4, 24
 Hire, De la, 204
 Hodograph, 119
 Hoist, mine, 8
 Hooke joint, 16, 50, 354
- Image, acceleration, 20, 128
 velocity, 20, 101
 Imaginary quantities, 372
 Inflection circle, 194, 199
 Instantaneous center, 15, 103
 absolute, 106
 acceleration, 417
 relative, 106
 Inversion, geometric, 180
 kinematic, 18, 55
 Inversors, 181
 Isometric perspective, 71
- Joint, ball-and-socket, 34
 Jonge, de, A. E. R., 21, 22
- Kant, 8
 Kardan universal joint (see Cardan
 universal joint)
 Kennedy, A. B. W., 17, 19, 24, 35, 106
 Kinematic analysis, 88, 130
 Kinematic chain, 53, 348
 Kinematic model, 68
 Kinematic synthesis, 18, 21, 88, 130
 Kinematics, 8, 14, 15
 Kinetics, 8
- Lagrange, 7
 Lanz, 12
- Leupold, J., 7, 24
 Line contact, 38
 Link, 52, 348
 Link-error equation, 317
 Linkage, 39
 cognate, 168, 176, 179
 deltoid, 78
 dwell, 81, 286
 equivalent, 63, 168
 spatial, 343
- Machine, 1, 2, 28
 elements of, 11
 simple, 2
 Matrix, 390
 method, 347, 352
 rank of, 391
 Mechanical components, 2
 Mechanical powers, 2
 Mechanism, 1, 18, 28, 54
 Bennett, 52, 85, 350
 Bricard, 85
 crank-and-rocker, 55, 77
 direct- and indirect-contact, 108
 double-crank, 55, 77
 double-rocker, 55, 77
 drag-link, 55
 Galloway, 78*n*.
 Goldberg, 85
 planar, 50
 planar four-revolute, 350
 quadric-crank, 40
 slider-crank, 44
 spatial, 50, 343
 spherical, 50
 spherical four-revolute, 350, 356
 straight-line, 179
 symmetric, 362
 two-revolute, two-spheric pair, 344,
 358
- Mehmke, 20
 Mill, grain, 5
 Minor, 385
 Model, kinematic, 68
 Mohr, 20
 Moivre, De, theorem, 376

- Monge, G., 11, 12, 24, 29
 Motion, absolute, 31, 92
 coupler-point, 7, 19
 planar, 49
 relative, 31, 92
 spatial, 50
 three-bar, 8, 19
 variable, 32
 Movability, criteria of, 21, 134
 Movable chain, 134
- Nerge, G., 48
 Notation, 91
 symbolic, 19, 64, 343
- Obelisk, Luxor, 18
 Vatican, 12
 Odometer, 4
 Oldham coupling, 55
- Pair, 17, 35, 347
 higher, 17, 38, 138
 lower, 17, 35
 variable, 35, 347
 wrapping, 36
 (*See also* Connectors)
 Parallel-motion, 41, 74
 Peaucellier, 16
 Poincot, L., 15, 23
 Points, accuracy, 139, 140
 spacing of, 140
 cardinal, 251
 center, 257, 260
 change, 78
 circle, 257, 262
 circular at infinity, 156*n.*
 coincident, 89
 cyclic, 156
 dead, 325
 double, 162
 imaginary, 154
 infinity, 155
 multiple, 152
 precision, 139
- Pole, 110, 218
 image, 253
 inflection, 199
 opposite, 257
 relative, 221
 slider-crank mechanism, 236
 triangle, 249
 Polygon, vector, 101, 128
 Polynomials, Chebyshev, 22, 142, 144
 Powers, mechanical, 2
 Pressure angle, 48
 Prony, 16, 150, 175
- Quadric-crank mechanism, 40
 Quadrilateral, opposite-pole, 257
- Rankine, W. J. M., 17, 25
 Rapson's slide, 66
 Restraint, 135
 Reuleaux, F., 2, 17-19, 25, 29, 34, 35, 38, 64, 75
 Revolute, 34
 Roberts, Richard, 16, 25
 Roberts, Samuel, 8, 19, 22, 25, 150
 Roberts-Chebyshev theorem, 154, 168, 337
 extensions of, 176
 Rocker, 77
 Rotary engine, 57
- Sarrus' rule, 384
 Savary, 204
 Scotch yoke, 55
 Singular foci, 160, 161
 circle of, 152
 Slider-crank mechanism, 44
 central, 45
 cognate, 176
 displacement equation of, 306
 eccentric, 45
 offset, 45
 poles of, 236
 Smith, R. H., 19, 20, 26

- Speed, 93
- Straight-line mechanism, 179
- approximate, Chebyshev, 180
 - Evans, 43, 180
 - Watt, 41, 180
 - true, Hart, 185
 - Peaucellier, 16, 181
- Structure, 53, 132
- Symbolic description, 65
- Symbolic notation, 19, 64, 343
- Synthesis, algebraic methods, 295
- approximate, 138
 - dimensional, 19, 21, 132, 138
 - exact, 138
 - geometric methods, 215
 - kinematic, 18, 21, 88, 130
 - number, 19, 21, 132
 - type, 19, 21, 132
- Three-center theorem, 106
- Transmission angle, 47, 319
- Universal joint, Hooke, 16, 50, 354
- Veldkamp, G. R., 198*n.*
- Velocity, absolute, 97
- angular, 93
 - difference, 100
 - displacement of IC, 196*n.*
 - IC, 115, 196
 - image, 101
 - linear, 93
 - pole, 196*n.*
 - polygon, 101
 - relative, 97, 100
- Vinci, Leonardo da, 5
- Vitruvius, P. M., 2-5, 26
- Waterworks, London Bridge, 10
- Marly, 11
- Watt, J., 7, 8, 26
- Whitworth quick-return, 56
- Willis, R., 8*n.*, 16, 26, 29, 70

