

Bayesian Marked Point Process Modeling for Generating Fully Synthetic Public Use Data with Point-Referenced Geography

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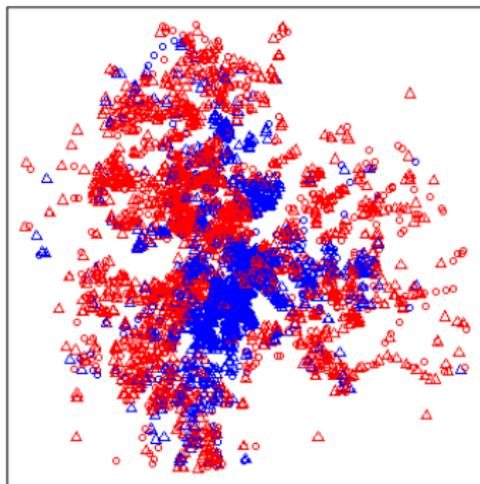
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The Problem

Suppose you want to release data to the public with the following information:

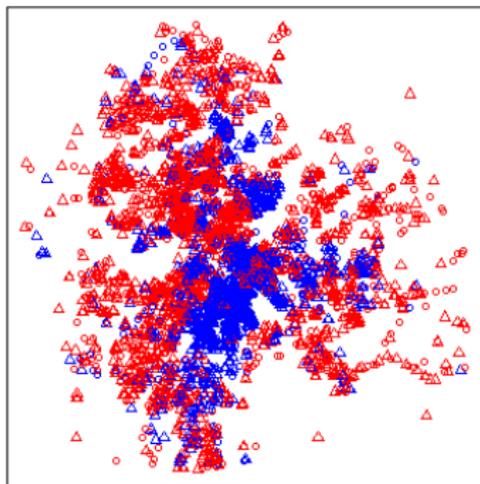
- ▶ Race
- ▶ Gender
- ▶ Income
- ▶ Spatial location



The Problem

Suppose you want to release data to the public with the following information:

- ▶ Race
- ▶ Gender
- ▶ Income
- ▶ Spatial location
- ▶ Sensitive information like disease status



- ▶ Releasing these data may present a disclosure risk

Some Current Options

- ▶ Release data at the aggregate level (e.g., county, state, etc.)
 - ▶ Useful for summarizing, but not individual-level, no fine spatial resolution
- ▶ Release synthetic (i.e., fake) data
 - ▶ Non-spatial: Plenty of options, including CART and model-based methods
 - ▶ Spatial: Spatial components are typically modeled simply as additional covariates (e.g., areal data modeled as a categorical covariate, etc.)...

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 - ▶ Non-spatial: Plenty of options, including CART and model-based methods
 - ▶ Spatial: Spatial components are typically modeled simply as additional covariates (e.g., areal data modeled as a categorical covariate, etc.)...
 - ▶ ... but do these methods preserve the spatial dependencies in the data?

Our solutions

- ▶ Want individual-level microdata with exact spatial locations and without the inherent disclosure risks
- ▶ Want to preserve spatial dependencies in the real data

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 - ▶ Generate L fully synthetic datasets
 - ▶ Say, $L = 10$ or $L = 100$
- ▶ Want to preserve spatial dependencies in the real data

Our solutions

- ▶ Want individual-level microdata with exact spatial locations and without the inherent disclosure risks
 - ▶ Generate L fully synthetic datasets
 - ▶ Say, $L = 10$ or $L = 100$
- ▶ Want to preserve spatial dependencies in the real data
 - ▶ Use a marked point process model
 - ▶ This will allow us to have categorical and non-categorical marks, as well as spatial locations, for each observation in our synthetic data

General strategy

1. Fit a hierarchical model to our data
 - ▶ We present a general framework here, but the exact model used will depend on what is most appropriate for a given dataset
2. Use posterior predictive distribution to generate fully synthetic datasets

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Components of marked point process model

We will build our marked point process sequentially using the following components

- ▶ Categorical marks
 - ▶ e.g., race, gender, etc.
- ▶ Spatial locations (given categories)
- ▶ Non-categorical marks (given spatial locations and categories)
 - ▶ e.g., income, age, etc.

Categorical mark model

Suppose our data consist of a total of K combinations of categorical marks, e.g., race, gender, etc., and let n_k denote the number of individuals belonging to the k -th mark group, $k = 1, \dots, K$. A natural choice for modeling the vector $\mathbf{n} = (n_1, \dots, n_K)'$ is a multinomial random variable

$$\mathbf{n} \mid N, \boldsymbol{\theta} \sim \text{Mult}(N, \boldsymbol{\theta}),$$

where $N = \sum_k n_k$ denotes the total sample size and $\boldsymbol{\theta} = (\theta_1, \dots, \theta_K)'$ denotes the vector of group probabilities.

Model for spatial locations

To model locations, we take an approach similar to that of Liang et al. (2009)

- ▶ Locations modeled as arising from a log-Gaussian Cox process
- ▶ Integral approximated using numerical integration

$$\begin{aligned} LGCP \{S_k \mid \lambda_k(\cdot), n_k\} &= \exp \left\{ - \int_D \lambda_k(\mathbf{s}) d\mathbf{s} \right\} \prod_{i=1}^{n_k} \lambda_k(\mathbf{s}_{i,k}) \\ &\approx \exp \left\{ - \frac{|D|}{T} \sum_{i=1}^{n_{ni}} \lambda_k(\mathbf{s}_{i,ni}) \right\} \prod_{i=1}^{n_k} \lambda_k(\mathbf{s}_{i,k}), \end{aligned}$$

where

- ▶ $\lambda_k(\mathbf{s}) = \exp \left[\mathbf{x}_\lambda(\mathbf{s})' \boldsymbol{\beta}_{\lambda|k} + w_{\lambda|k}(\mathbf{s}) \right]$ is the intensity surface for category k
- ▶ $\mathbf{x}_\lambda(\mathbf{s})$ is a vector of spatial predictors with a corresponding vector of regression coefficients, $\boldsymbol{\beta}_{\lambda|k}$
- ▶ $w_{\lambda|k}(\mathbf{s})$ is a spatial random effect

Model for spatial locations, cont.d

For large values of n_{ni} (the number of integration points), this can be computationally burdensome. As such, we've used the *predictive process* model of Banerjee et al. (2008) to reduce the dimension to a more manageable level

$$\begin{aligned} LGCP \{S_k \mid \lambda_k(\cdot), n_k\} &= \exp \left\{ - \int_D \lambda_k(\mathbf{s}) d\mathbf{s} \right\} \prod_{i=1}^{n_k} \lambda_k(\mathbf{s}_{i,k}) \\ &\approx \exp \left\{ - \frac{|D|}{T} \sum_{i=1}^{n_{ni}} \tilde{\lambda}_k(\mathbf{s}_{i,ni}) \right\} \prod_{i=1}^{n_k} \tilde{\lambda}_k(\mathbf{s}_{i,k}), \end{aligned}$$

where $\tilde{\lambda}_k(\mathbf{s}_{i,k})$ denotes the low-rank approximation of the intensity surface corresponding to a predictive process model on $w_{\lambda|k}(\mathbf{s})$

Non-categorical marks model

Given our categories and our locations, we can model non-categorical marks using standard approaches from the geostatistical literature. For instance,

$$Y_k(\mathbf{s}) \sim N(\mathbf{x}_Y(\mathbf{s})'\boldsymbol{\beta}_{Y|k} + w_{Y|k}(\mathbf{s}), \sigma_k^2),$$

for a continuously varying response or

$$Y_k(\mathbf{s}) \sim \text{Pois} \left(\exp \left\{ \mathbf{x}_Y(\mathbf{s})'\boldsymbol{\beta}_{Y|k} + w_{Y|k}(\mathbf{s}) \right\} \right),$$

for a positive integer-valued variable such as age.

Again, we may choose to use a predictive process approach to achieve dimension reduction.

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Generating fully synthetic microdata

Having fit our hierarchical model and obtained posterior distributions for all of our model parameters, we can now generate our L synthetic datasets.

First, we assign our $N^{\dagger(\ell)}$ synthetic individuals to groups

$$\mathbf{n}^{\dagger(\ell)} \mid N^{\dagger(\ell)}, \boldsymbol{\theta}^{(\ell)} \sim \text{Mult} \left(N^{\dagger(\ell)}, \boldsymbol{\theta}^{(\ell)} \right),$$

where $\ell = 1, \dots, L$. For the ease of notation, $\boldsymbol{\theta}^{(\ell)}$ denotes the ℓ th post-burn-in sample from our posterior.

Generating fully synthetic microdata, cont.d

Next, we sample geographies for these individuals from

$$\mathcal{S}_k^{\dagger(\ell)} \mid \tilde{\lambda}_k^{(\ell)}(\cdot), n_k^{\dagger(\ell)} \sim \text{LGCP} \left\{ \tilde{\lambda}_k^{(\ell)}(\cdot), n_k^{\dagger(\ell)} \right\}, \quad k = 1, \dots, K.$$

For computational reasons, these points will be sampled *with replacement* — i.e., it is possible for multiple individuals to be at the same location.

Finally, we sample our non-categorical marks, say

$$Y_k^{\dagger(\ell)}(\mathbf{s}_i^{\dagger(\ell)}) \mid \mu_k^{(\ell)}(\mathbf{s}_i^{\dagger(\ell)}), \sigma_k^{2(\ell)} \sim N\left(\mu_k^{(\ell)}(\mathbf{s}_i^{\dagger(\ell)}), \sigma_k^{2(\ell)}\right), \quad k = 1, \dots, K.$$

Evaluating utility of the synthetic data

- ▶ To investigate spatial dependence, we estimate the K and L functions

$$\hat{K}(h) = \frac{|D_s|}{N} \sum_{\substack{i=1 \\ i \neq j}}^N \sum_{j=1}^N I(\|\mathbf{s}_i - \mathbf{s}_j\| \leq h) / N$$

$$\hat{L}(h) = \sqrt{\hat{K}(h)/\pi} - h,$$

where $|D_s|$ is the area of spatial domain.

- ▶ We also make comparisons of parameter estimates from various statistical models of interest

Assessing disclosure risk in synthetic data

First we define two terms/expressions:

- ▶ *spatially close*: Two locations are said to be spatially close if the distance between them is less than some ϵ_s ; denoted $\sim \mathbf{s}_0$
- ▶ *similar attributes*: Two individuals are said to have similar attributes if they belong to the same mark categories and their non-categorical marks are within ϵ_a of each other; denoted $\sim Y_k(\mathbf{s}_0)$

Assessing disclosure risk in synthetic data, cont.d

- ▶ **“Type S Risk”**: If you know the **spatial location**, how well can you estimate the **attributes**?

$$\begin{aligned} P(\sim Y_k(\mathbf{s}_0) \mid \sim \mathbf{s}_0) &\approx p_s^{\dagger(\ell)}(Y_k(\mathbf{s}_0), \mathbf{s}_0) \\ &= \frac{\sum_i I\{Y_k^{\dagger(\ell)}(\mathbf{s}_i^{\dagger(\ell)}) \sim Y_k(\mathbf{s}_0) \mid \mathbf{s}_i^{\dagger(\ell)} \sim \mathbf{s}_0\}}{\sum_i I\{\mathbf{s}_i^{\dagger(\ell)} \sim \mathbf{s}_0\}} \end{aligned}$$

for $\ell = 1, \dots, L$

- ▶ **“Type A Risk”**: If you know the **attributes**, how well can you estimate the **spatial location**?

$$\begin{aligned} P(\sim \mathbf{s}_0 \mid \sim Y_k(\mathbf{s}_0)) &\approx p_a^{\dagger(\ell)}(Y_k(\mathbf{s}_0), \mathbf{s}_0) \\ &= \frac{\sum_i I\{\mathbf{s}_i^{\dagger(\ell)} \sim \mathbf{s}_0 \mid Y_k^{\dagger(\ell)}(\mathbf{s}_i^{\dagger(\ell)}) \sim Y_k(\mathbf{s}_0)\}}{\sum_i I\{Y_k^{\dagger(\ell)}(\mathbf{s}_i^{\dagger(\ell)}) \sim Y_k(\mathbf{s}_0)\}} \end{aligned}$$

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Durham, NC mortality data

These data consist of addresses for $N = 6294$ individuals with the following attributes

- ▶ Race (black/white)
- ▶ Gender
- ▶ Cause of death (cancer-related vs. other)
- ▶ Education (< HS, HS, some college)
- ▶ Age

We model our data as having 24 categorical groups and assume a (truncated) Poisson distribution for age. Based on these data, we will generate $L = 100$ synthetic datasets, each comprised of N synthetic individuals

Comparison of spatial dependencies

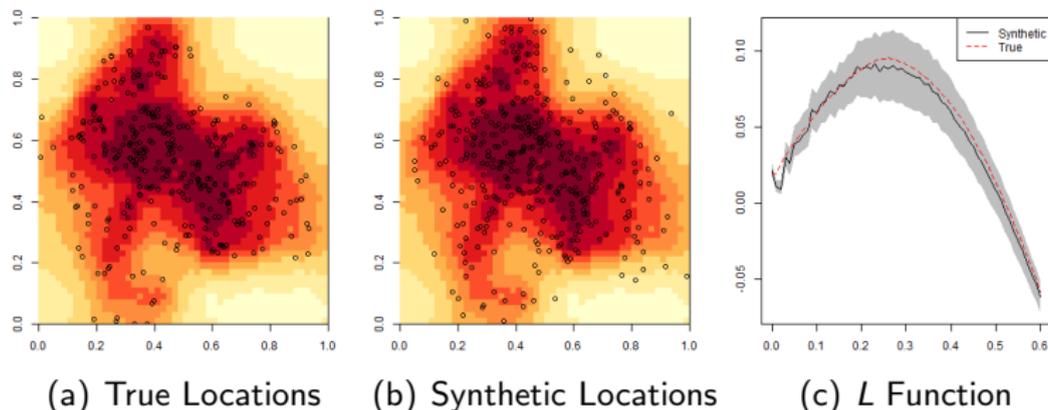


Figure 1: Panels (a) and (b) display locations for one group of observations from the true and a synthetic dataset, respectively, both overlaid on our estimated intensity surface. Panel (c) displays $\hat{L}(h)$ over a range of values of h for our true (dashed red line) and synthetic data (black line), along with the pointwise empirical 95% CI from the synthetic data (gray band).

Comparison of parameter estimates

We may also wish to compare parameter estimates from the following models:

- ▶ Poisson Regression:

$$\text{Age}_i \sim \text{Pois}(\lambda_i) \text{ where } \log(\lambda_i) = \sum_{j=1}^{24} \beta_{1j} I(\text{Group}_i = j),$$

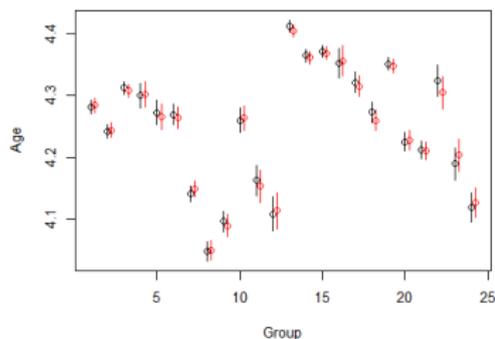
and Group_i is an integer between 1 and 24 denoting which combination of race, gender, education level, and cause of death the individual belongs to.

- ▶ Logistic Regression:

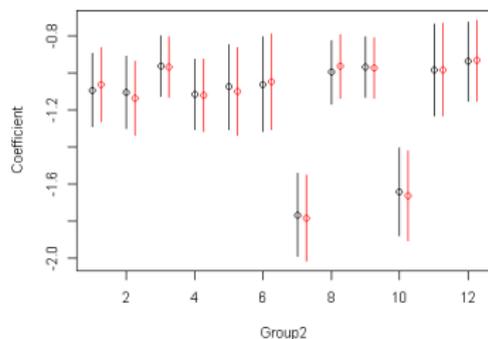
$$\text{CoD}_i \sim \text{Ber}(\pi_i) \text{ where } \text{logit}(\pi_i) = \sum_{j=1}^{12} \beta_{2j} I(\text{Group2}_i = j)$$

and Group2_i be an integer between 1 and 12 denoting which combination of race, gender, and education level each individual belongs to.

Comparison of parameter estimates, cont.d



(a) Poisson Regression: Age



(b) Logistic Regression: Cause of Death

Figure 2: Comparison of parameter estimates from a Poisson regression on age and a logistic regression on the cause of death. Circles denote mean estimates while bars denote the 95% CI. Estimates from the real data are displayed in black, while estimates obtained from the synthetic data are displayed in red.

Risk Assessment

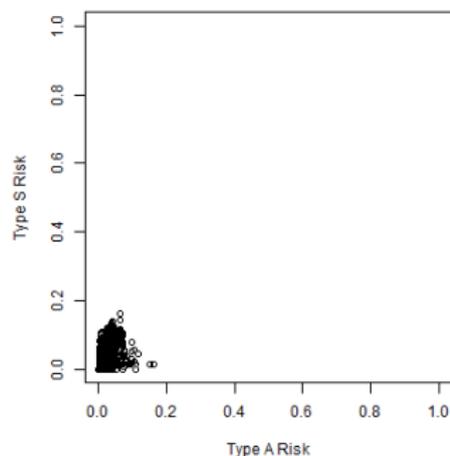


Figure 3: Comparisons of the estimated Type S Risk versus the estimate Type A Risk in our mortality example.

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Summary

- ▶ We have used a fully Bayesian framework to generate fully-synthetic microdata for the purpose of disclosure limitation
- ▶ While not explicitly discussed here, we believe our framework can be quite computationally efficient by taking advantage of dimension reduction techniques as well as parallel computing
- ▶ Based on the results from our mortality dataset, our synthetic data offer a high degree of data utility without a substantial disclosure risk

Thanks!

My collaborators:

- ▶ Scott Holan (Missouri)
- ▶ Chris Wikle (Missouri)
- ▶ Jerry Reiter (Duke)

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