

OPTIMAL SATURATED MAIN EFFECT PLANS
FOR THE 2^n FACTORIAL AND v, k, λ
CONFIGURATIONS

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ABSTRACT

This paper shows that the saturated main effect plan for the 2^n factorial consisting of the $n+1$ treatment combinations $00\dots 0, 011\dots 1, 1011\dots 1, \dots, 11\dots 10$ is optimal (in the sense of maximum absolute value of the determinant of the design matrix,) in the class of all saturated main effect plans where the factors occur n times at the low level.

1] Paper No. BU-198 of the Biometrics Unit and No. 587 of the Department of Plant Breeding and Biometry, Cornell University, Ithaca, New York.

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1. Introduction and Summary. Consider the estimation of the n main effects and the overall mean in the 2^n factorial with $n+1$ observations taken at $n+1$ treatment combinations. Such a plan is known in the literature as a saturated main effect plan (e.g. see Addelman [1963]). Following Ryser [1963] we define a v, k, λ configuration to be an arrangement of v elements into v sets such that each set contains exactly k distinct elements and such that each pair of sets has exactly λ elements in common, where $0 < \lambda < k < v$. In BIB terminology a v, k, λ configuration is a balanced incomplete block design with parameters $v, b=v, k=r, r$ and λ . The $v \times v, (0,1)$ -incidence matrix A of a v, k, λ configuration satisfies the properties:

$$(1.1) \quad A'A = AA'$$

$$(1.2) \quad |\det A| = k(k-\lambda)^{\frac{1}{2}(v-1)}$$

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Now, let Q be a $(0,1)$ -matrix of order v , containing exactly t 1's. Let $k = t/v$ and set $\lambda = k(k-1)/(v-1)$, with $0 < \lambda < k < v$, then Ryser [1956] has proved that:

$$(1.3) \quad |\det Q| \leq k(k-\lambda)^{\frac{1}{2}(v-1)}$$

with equality holding if and only if Q is the incidence matrix of a v, k, λ configuration.

In this paper, we show that the saturated main effect plan for the 2^n factorial consisting of the treatment combinations $00\dots 0, 011\dots 1, 1011\dots 1, \dots, 11\dots 10$ is optimal (in the sense of maximum absolute value of the determinant of the design matrix) in the class of all saturated main effect plans where the factors occur exactly $2n$ times at the low level. We prove this by utilizing Williamson's [1946] and Ryser's [1956] results.

2. Saturated main effect plans, $(0,1)$ -matrices and v, k, λ configurations.

Let X_{n+1} be the $(-1,1)$ -design matrix of order $(n+1)$ of any saturated main effect plan of the 2^n factorial. The first column of X_{n+1} consists of 1's, i.e. X is in semi-normalized form (see Raktoc and Federer [1969]). In searching for an optimal plan in the sense of maximum absolute value of the determinant of X_{n+1} , Williamson [1946] has shown that one may always take the first row of X to consist of -1's, except the element in the first column. Relating this result to saturated main effect plans of the 2^n factorial, we have the following theorem:

THEOREM 2.1

The study of optimal saturated main effect plans for the 2^n factorial in the sense of maximum absolute value of the determinant of X_{n+1} is equivalent to the study of the class of seminormalized square $(-1,1)$ -matrices with -1's as entries in the first row except the element in the first column.

Now, following Williamson [1946] or Raktoc and Federer [1969] we obtain the following relation by adding the first column of X to all other columns:

$$(2.1) \quad |\det X_{n+1}| = 2^n |\det X_n^*|$$

where X_n^* is an $n \times n$ matrix of 0's and 1's. This result leads us to a slightly different theorem than the one obtained by Raktoc and Federer [1969], viz.:

THEOREM 2.2

The study of optimal saturated main effect plans for the 2^n factorial in the sense of maximum absolute value of the determinant of the $(-1,1)$ -matrix X_{n+1} is equivalent to the study of the class of $(0,1)$ -matrices in the sense of maximum absolute value of the determinant of X_n^* .

Historically, the study of optimal saturated main effect plans has been divided into two categories, namely the case where $n+1 = 4t$ (we assume $n+1 \geq 2$), so that Hadamard matrices are conjectured to exist and the non-orthogonal case with $n+1 \neq 4t$. Plackett and Burman [1946] have given tables of orthogonal main effect plans, while Raghavarao [1959] has studied optimal saturated main effect plans assuming that $X_{n+1}' X_{n+1}$ is of the form $a I_{n+1} + b J_{n+1}$. The plans corresponding to these two classes has been recently characterized by Raktoc and Federer [1969].

The fundamental paper by Williamson [1946] provides us optimal matrices \dot{X}_n^* for $n = 2, 3, 4, 5$ and 6. We exhibit here examples of these for the benefit of the reader:

$$\dot{X}_2^* = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad \dot{X}_3^* = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

$$\dot{X}_4^* = \begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \end{bmatrix}, \quad \dot{X}_5^* = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 & 1 \end{bmatrix}$$

$$\dot{X}_6^* = \begin{bmatrix} 1 & 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 1 & 1 & 1 & 0 \end{bmatrix}$$

The absolute values of the determinants of these five matrices are 1, 2, 3, 5 and 9 respectively. The optimal saturated main effect plans are simply obtained by adjoining the treatment combination 00...0 as a row to each of the matrices above. The design matrices are obtained by identifying 0's by -1's and by bordering the resulting matrix with a column of 1's. The determinant of X_{n+1}^* is then simply obtained from (2.1).

Now, let t denote the number of 1's in the matrix X_n^* , then it follows that for the 2^n factorial the range of t is:

$$(2.2) \quad n \leq t \leq n^2 - n + 1$$

Set $k = t/n$ and $\lambda = k(k-1)/n^2(n-1)$ then from Ryser [1956] we know that for given t and $0 < \lambda < k < n$ the result (1.3) is valid. When t is not fixed, then Williamson [1946], Ryser [1956] and later on Raktov and Federer [1969] have shown that:

$$(2.3) \quad |\det X_n^*| \leq 2^{-n} (n+1)^{\frac{n+1}{2}}$$

with equality holding if and only if X_n^* is obtained from a Hadamard matrix, i.e. in the case of equality with $n+1 = 4t$, we have:

$$(2.4) \quad |\det X_n^*| = 2^{-(4t-1)} (4t)^{2t}$$

The result (2.3) of Williamson [1946] and Ryser [1956] is in reality stronger than the same result obtained by Raktoc and Federer [1969], since the class of (0,1)-matrices considered by the last two authors were of the semi-normalized type and of order $(n+1)$. Also, in the case where (2.4) holds Ryser [1956] has proved that $v = 4\lambda - 1$ ($=n$), $k = 2\lambda$ and $\lambda = \lambda$ for the incidence matrix of the v, k, λ configuration. In using (1.3) we will presently be concerned with the attainment of this upperbound, i.e. with the existence and construction of a $v=n, k, \lambda$ configuration for every value of t in the range given by (2.2). Hence, we have another equivalence set forth in the following theorem:

THEOREM 2.3

The study of optimal saturated main effect plans for the 2^n factorial in the sense maximum absolute value of the $(-1,1)$ -matrix X_{n+1} is equivalent to the study of each class of $(0,1)$ -matrices corresponding to each value of t as given by (2.2) in the sense of maximum absolute value of the determinant of X_n^* .

3. Optimal plans and v, k, λ configurations of a certain type. In utilizing

$$(1.3) \text{ we have } k = t/n \text{ and } \lambda = \frac{t(t-n)}{n^2(n-1)}; \text{ both of these quantities must equal}$$

positive integers in order to make sense as a v, k, λ configuration. This implies that t must equal a multiple of n . In other words, we have to consider the values $n, 2n, 3n, \dots, (n-1)n$ for t . But from $\lambda = t(t-n)/n^2(n-1)$ it then follows that λ will be a positive integer if and only if $t = n(n-1)$.

Hence, for a given 2^n factorial, there will be a $v=n$, $k=n-1$, $\lambda=n-2$ configuration if and only if $t = (n-1)n$. This implies that the upperbound (1.3) will be achieved if and only if $t = (n-1)n$. Hence we have proved the following theorem:

THEOREM 3.1

The upperbound (1.3) is achievable for the class of saturated main effect plans for the 2^n factorial if and only if the number of 1's in X_n^* is equal to $(n-1)n$.

That there actually exist X_n^* 's with $t = (n-1)n$, such that these will be incidence matrices of $v=n$, $k=n-1$, $\lambda=n-2$ configurations can be readily seen by considering the saturated main effect plan consisting of the origin $00\dots 0$ and the treatment combinations having exactly one factor at the low level, i.e., $011\dots 1$, $1011\dots 1$, \dots , $11\dots 10$. Here $X_n^* = -I_n + J_n$, where I_n is an $n \times n$ identity matrix and J_n is an $n \times n$ matrix of 1's. It is easily verified that for this plan the following is true:

$$(3.1) \quad |\det X_n^*| = (n-1) \text{ and } |\det X_{n+1}| = 2^n(n-1)$$

Hence, (1.2) is satisfied and since we can also verify that (1.1) is true, we have the following theorem:

THEOREM 3.2

For the 2^n factorial with $t = (n-1)n$ there exists an optimal saturated main effect plan corresponding to the $v=n$, $k=n-1$, $\lambda=n-2$ configuration.

4. Discussion. In this paper we have looked at a subset of the possible $\binom{2^n}{n+1}$ saturated main effect plans of the 2^n factorial, namely those having

exactly $t = (n-1)n$ 1's in the matrix X_n^* . For this class we have exhibited an optimal plan corresponding to a $v=n$, $k=n-1$, $\lambda=n-2$ configuration. Observe that X_2^* , X_3^* and X_4^* of Williamson [1956] are of the type given by theorem 3.2; X_5^* and X_6^* are on the other hand not of the type, as obviously they do not belong to the class having t equal to $(n-1)n$. As can be observed, the major problem still remains because we have in this paper not touched upon classes corresponding to other values of t (i.e. $t \neq (n-1)n$). This problem is currently under research.

5. Literature.

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